

Understanding the relativistic 2-body problem: Gravitational Waves and Numerical Relativity

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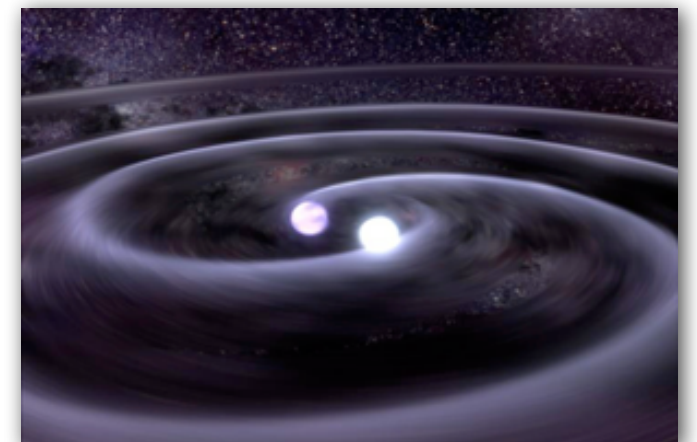
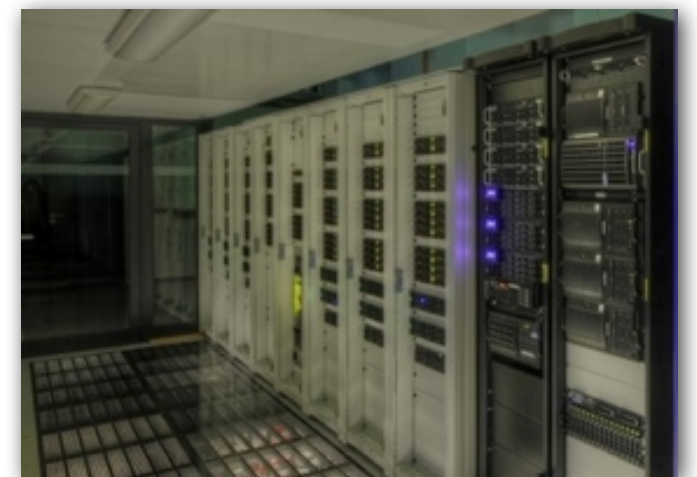
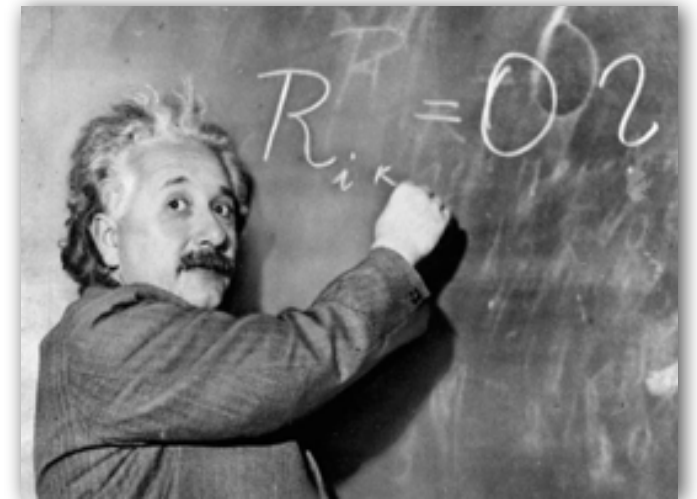


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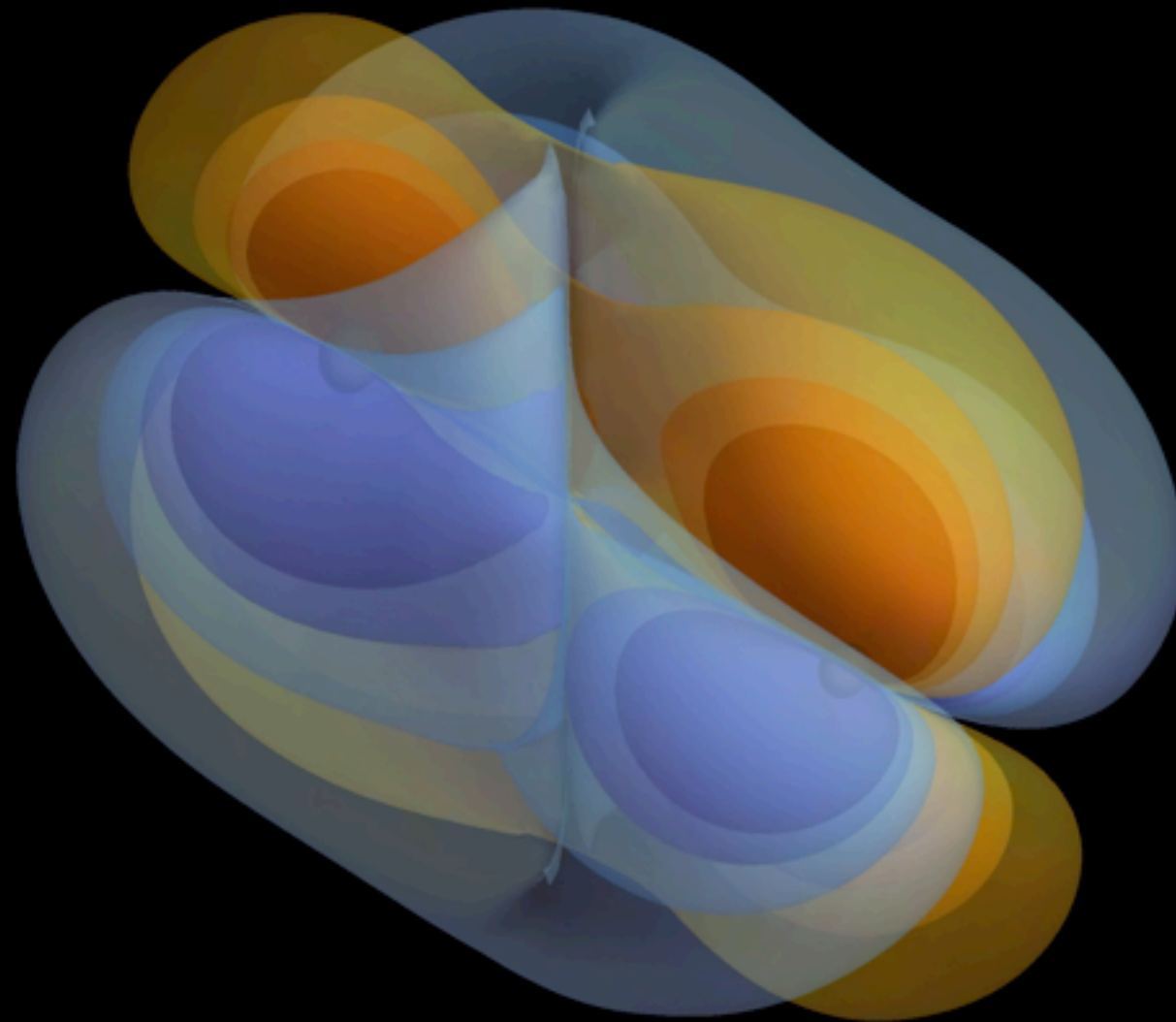
Modern Aspects of Gravitational Theory
Jena, 31st May, 2017

Overview

- Numerical Relativity
 - Physics, mathematics, numerics, computing, software
- Gravitational waves
 - Waveform modelling and LIGO
 - Waveforms from eccentric binaries
- Outlook



130.5 ms

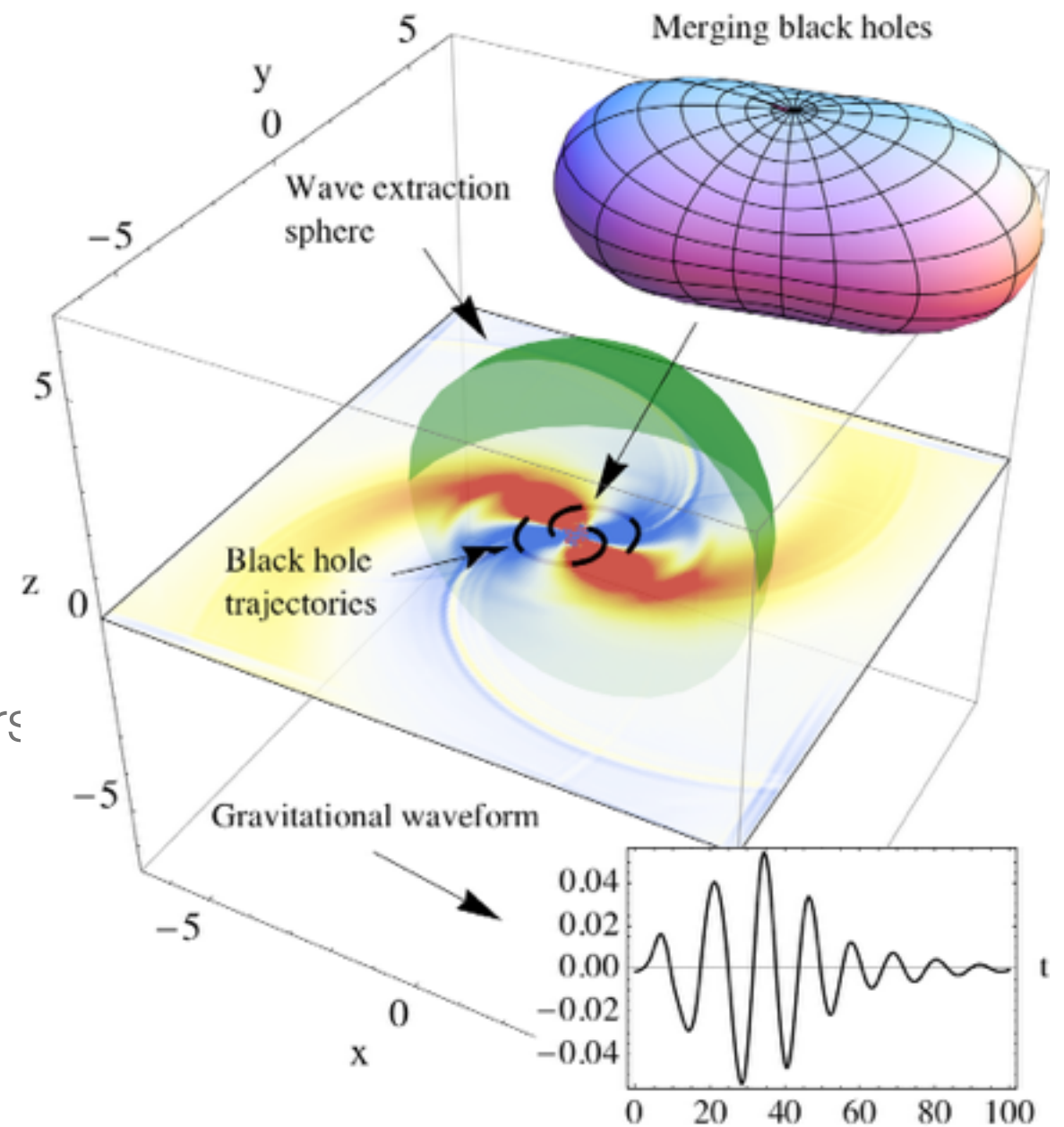


1. Numerical Relativity

Open source simulation of merger of
GW150914
[Wardell, IH, Bentivegna]
einstein toolkit.org/gallery/bbh

Numerical Relativity: Physics

- How does matter and geometry **evolve in time** in General Relativity?
- Some highlights:
 - Binary black hole and neutron star mergers: **test GR** and **high density** physics
 - Supernova core collapse
 - Gravitational wave templates for detectors
 - Cosmology: e.g. how does **light propagate** in an inhomogeneous spacetime? [Bentivegna, Korzynski and IH, 2016]
 - Mathematical relativity (singularity theorems), etc



Compact binary simulation in NR

Numerical Relativity: Maths

$$R_{\mu\nu} - \frac{1}{2}Rg_{\mu\nu} = 8\pi T_{\mu\nu}$$

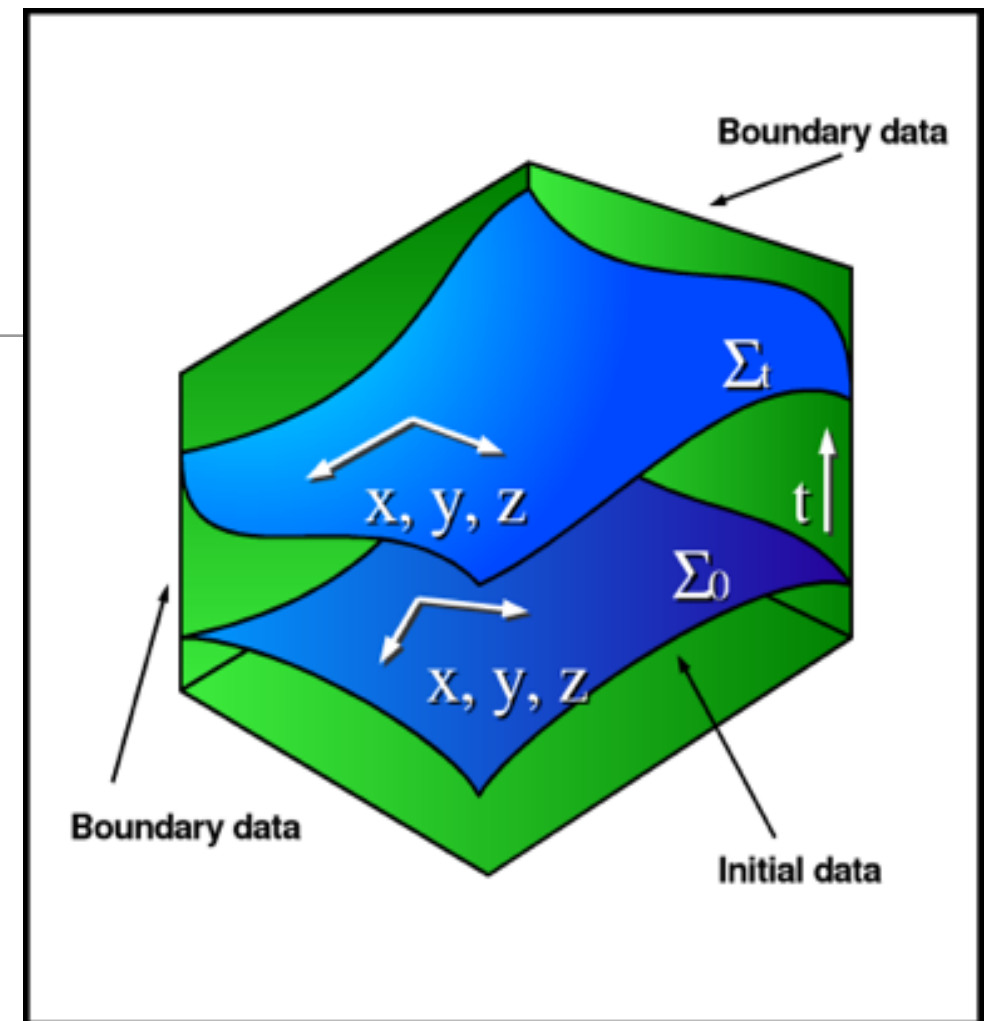
- 10 coupled nonlinear 2nd order partial differential equations:

$$\begin{aligned} {}^{(4)}R_{\mu\nu} &\equiv \frac{1}{2}g^{\sigma\rho}(g_{\sigma\nu,\mu\rho} + g_{\mu\rho,\sigma\nu} - g_{\sigma\rho,\mu\nu} - g_{\mu\nu,\sigma\rho}) \\ &\quad + g^{\sigma\rho}(\Gamma^m_{\mu\rho}\Gamma_{m\sigma\nu} - \Gamma^m_{\mu\nu}\Gamma_{m\sigma\rho}) \\ \Gamma^\mu_{\nu\sigma} &\equiv \frac{1}{2}g^{\mu\rho}(g_{\rho\nu,\sigma} + g_{\rho\sigma,\nu} - g_{j\sigma,\rho}) \end{aligned}$$

Formulate as **initial boundary value problem** by projecting onto a **foliation** of 3D $t=\text{const}$ slices:

$$\frac{\partial}{\partial t}u(t, x^i) = F(u(t, x^i), \partial u(t, x^i), \partial^2 u(t, x^i))$$

- ~25 eqs/variables - **complicated, nonunique,** issues of **well-posedness**



- Initial data ($t=0$) evolved forward in time with **evolution equations**
- Also get **constraint equations** on each $t=\text{const}$ slice

Einstein equations in 3+1 form

$$\begin{aligned}
 \partial_t \hat{\phi}_\kappa &= \frac{2}{\kappa} \hat{\phi}_\kappa \alpha K + \beta^i \partial_i \hat{\phi}_\kappa - \frac{2}{\kappa} \hat{\phi}_\kappa \partial_i \beta^i, \\
 \partial_t \tilde{\gamma}_{ab} &= -2\alpha \tilde{A}_{ab} + \beta^i \partial_i \tilde{\gamma}_{ab} + 2\tilde{\gamma}_{i(a} \partial_{b)} \beta^i \\
 &\quad - \frac{2}{3} \tilde{\gamma}_{ab} \partial_i \beta^i, \\
 \partial_t K &= -D_i D^i \alpha + \alpha (A_{ij} A^{ij} + \frac{1}{3} K^2) + \beta^i \partial_i K, \\
 \partial_t \tilde{A}_{ab} &= (\hat{\phi}_\kappa)^{\kappa/3} (-D_a D_b \alpha + \alpha R_{ab})^{\text{TF}} + \beta^i \partial_i \tilde{A}_{ab} \\
 &\quad + 2\tilde{A}_{i(a} \partial_{b)} \beta^i - \frac{2}{3} \tilde{A}_{ab} \partial_i \beta^i, \\
 \partial_t \tilde{\Gamma}^a &= \tilde{\gamma}^{ij} \partial_i \beta_j \beta^a + \frac{1}{3} \tilde{\gamma}^{ai} \partial_i \partial_j \beta^j - \tilde{\Gamma}^i \partial_i \beta^a \\
 &\quad + \frac{2}{3} \tilde{\Gamma}^a \partial_i \beta^i - 2\tilde{A}^{ai} \partial_i \alpha \\
 &\quad + 2\alpha (\tilde{\Gamma}_{ij}^a \tilde{A}^{ij} - \frac{\kappa}{2} \tilde{A}^{ai} \frac{\partial_i \hat{\phi}_\kappa}{\hat{\phi}_\kappa} - \frac{2}{3} \tilde{\gamma}^{ai} \partial_i K),
 \end{aligned}$$

$$\begin{aligned}
 R_{ij} &= \tilde{R}_{ij} + R_{ij}^\phi, \\
 R_{ij}^\phi &= -2\tilde{D}_i \tilde{D}_j \phi - 2\tilde{\gamma}_{ij} \tilde{D}^k \tilde{D}_k \phi + 4\tilde{D}_i \phi \tilde{D}_j \phi - 4\tilde{\gamma}_{ij} \tilde{D}^k \phi \tilde{D}_k \phi, \\
 \tilde{R}_{ij} &= -\frac{1}{2} \tilde{\gamma}^{lm} \partial_l \partial_m \tilde{\gamma}_{ij} + \tilde{\gamma}_{k(i} \partial_{j)} \tilde{\Gamma}^k + \tilde{\Gamma}^k \tilde{\Gamma}_{(ij)k} \\
 &\quad + \tilde{\gamma}^{lm} (2\tilde{\Gamma}^k_{l(i} \tilde{\Gamma}_{j)km} + \tilde{\Gamma}^k_{im} \tilde{\Gamma}_{klj}).
 \end{aligned}$$

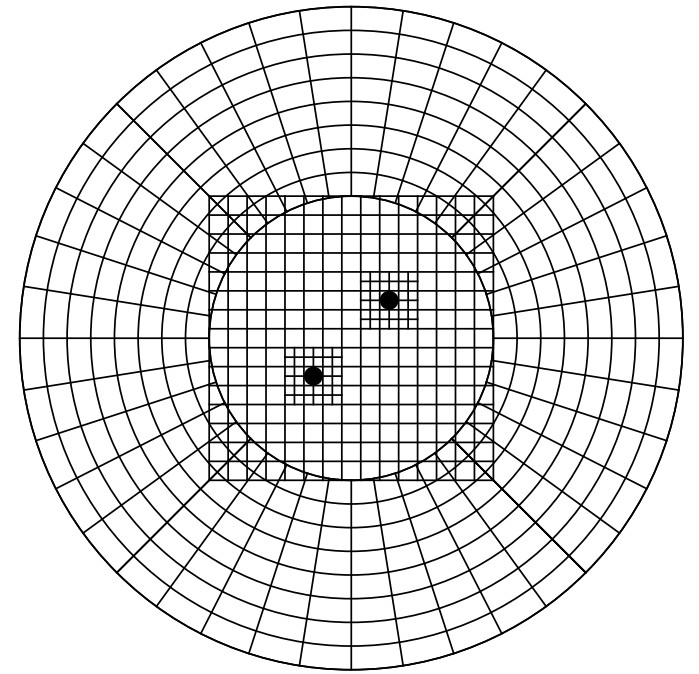
$$\begin{aligned}
 \partial_t \alpha - \beta^i \partial_i \alpha &= -2\alpha K, \\
 \partial_t \beta^a - \beta^i \partial_i \beta^a &= \frac{3}{4} \alpha B^a, \\
 \partial_t B^a - \beta^j \partial_j B^i &= \partial_t \tilde{\Gamma}^a - \beta^i \partial_i \tilde{\Gamma}^a - \eta B^a,
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{H} &\equiv R^{(3)} + K^2 - K_{ij} K^{ij} = 0, \\
 \mathcal{M}^a &\equiv D_i (K^{ai} - \gamma^{ai} K) = 0.
 \end{aligned}$$

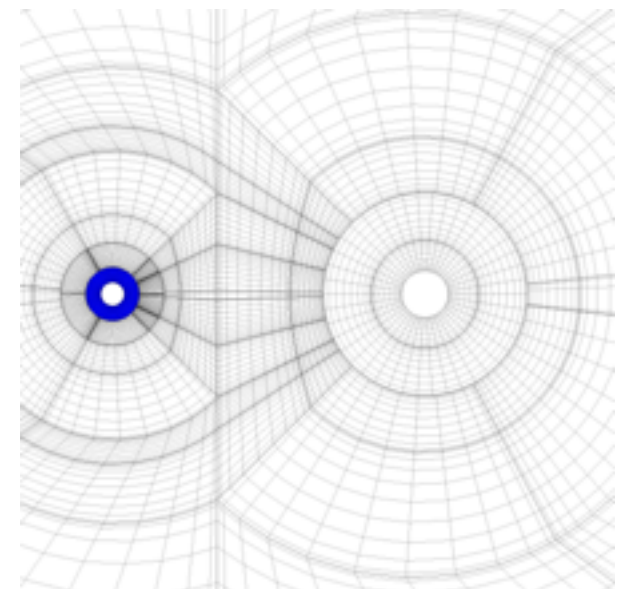
- Now expand components...

Numerical Relativity: Numerics

- Strong field: numerical where all else fails
- State vector of solution on a **3D grid** of points
- Spatial derivatives:
 - High-order **finite differencing**; or
 - **Spectral** collocation
- **Adaptive mesh refinement** in space and time
- **Formal stability**
 - First order in time, **second order** in space; standard methods inapplicable. **Stability** proved for certain formulations
[Calabrese, IH and Husa, 2006]



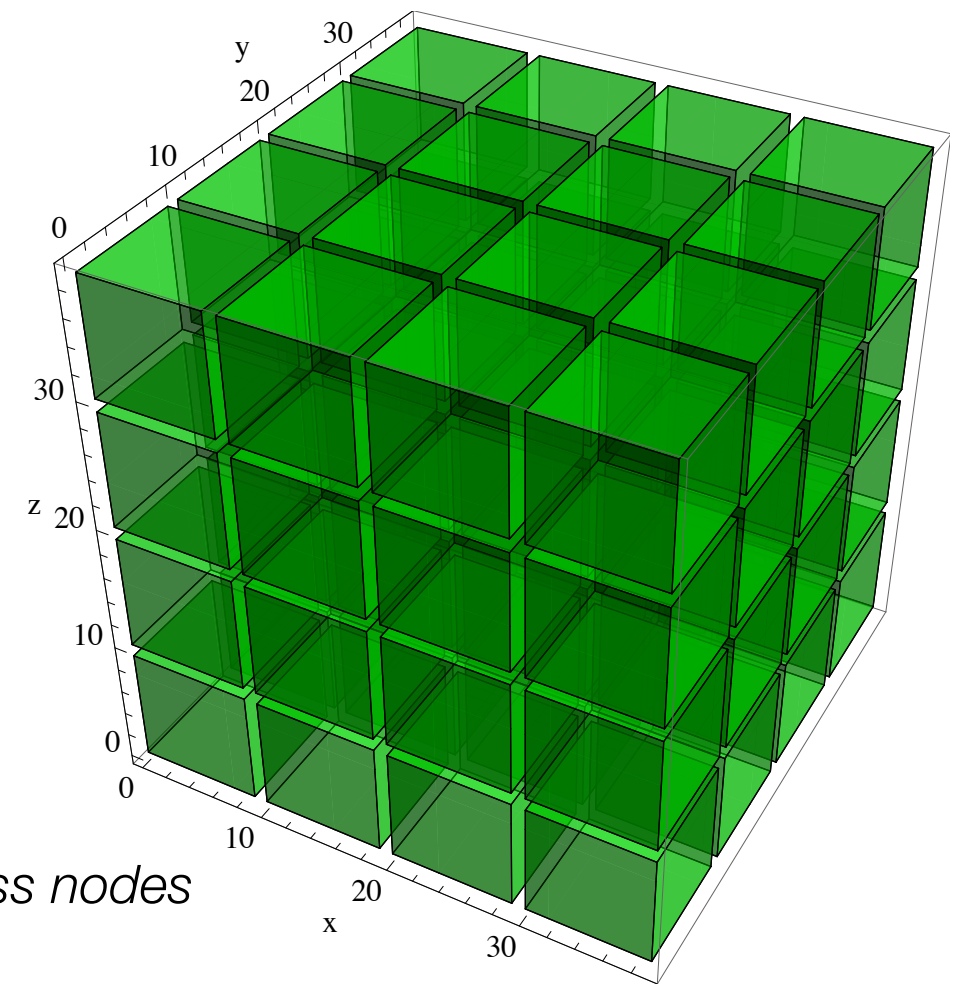
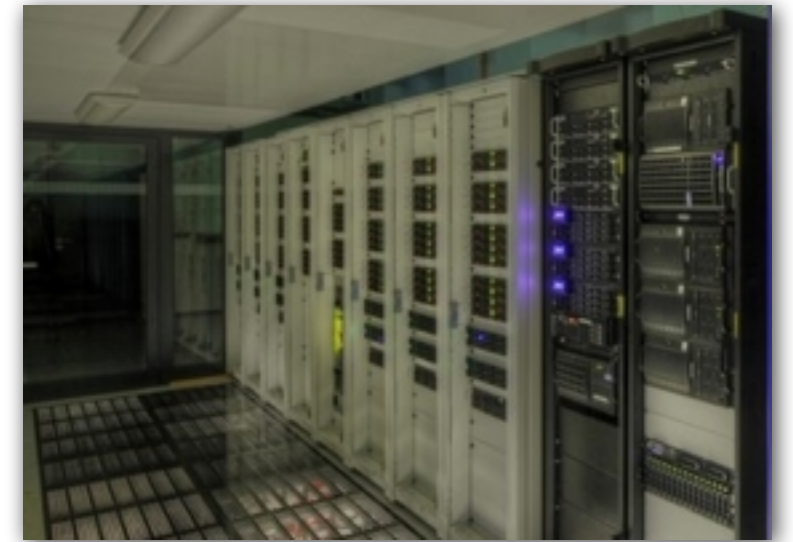
Einstein Toolkit code



SpEC code

Numerical Relativity: Computing

- Simulations: 100 - **1000 cores**, days/weeks/months
- Challenges:
 - **Parallel scalability** (many variables per grid point)
 - Complicated **communication** patterns of AMR
 - Use of modern accelerator architectures:
 - **GPUs**: first BBH simulation [Blazewicz, IH et al, 2013]
 - **Intel MIC** systems (Intel "Knights Landing") – work in progress
- Load imbalance: development of task-based scheduling

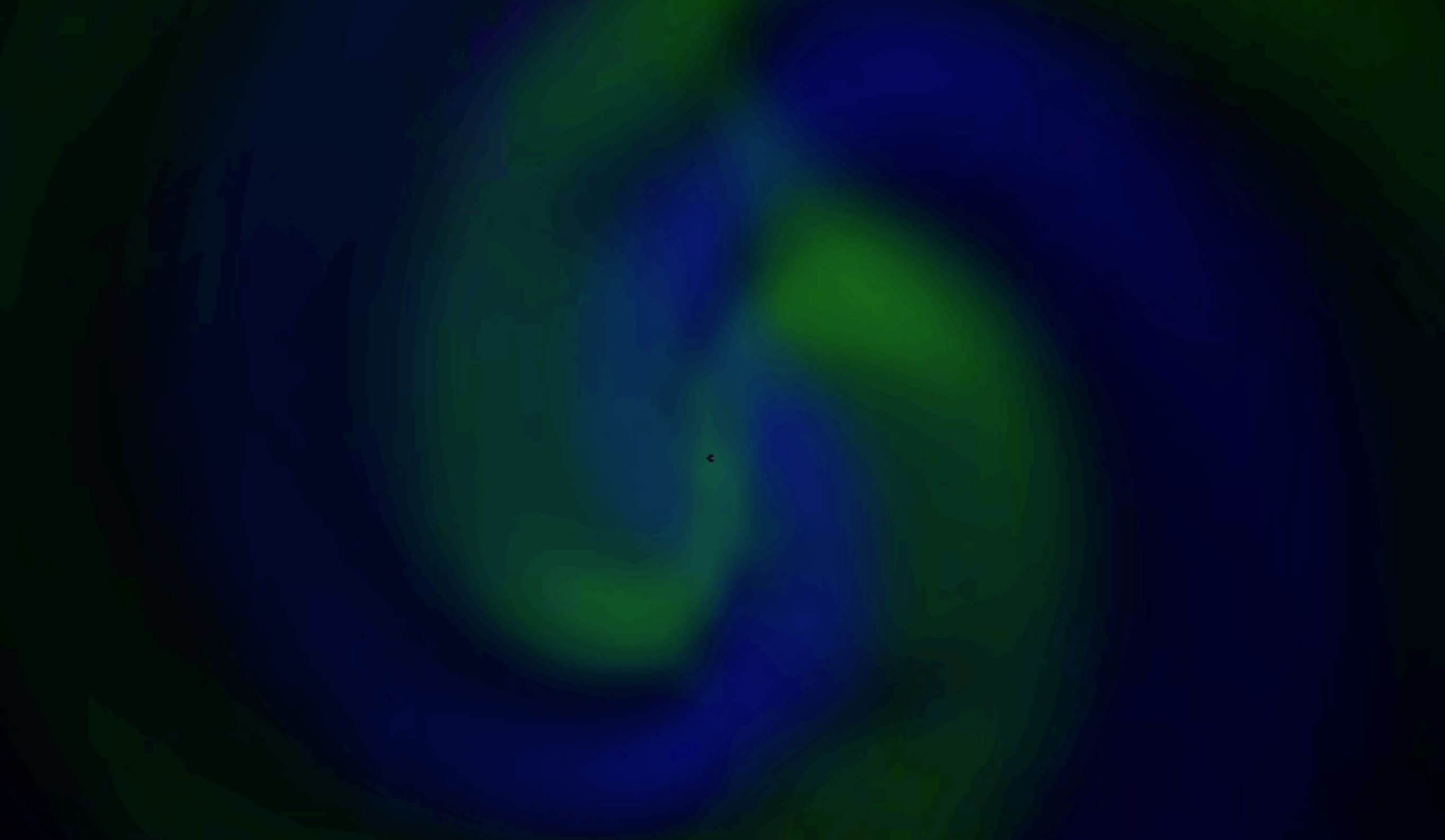


Decomposition of a simple numerical domain across nodes

Numerical Relativity: Software



- Einstein Toolkit (einstein toolkit.org):
 - **Open-source** collection of relativity codes [*Löffler, ..., IH et al., 2012*]
 - Based on Cactus, a software **framework** for HPC: portable, established, successful (Gordon Bell prize 2001)
 - **Automated** code generation from tensorial descriptions [*Husa, IH and Lechner, 2004*]
 - **Production**-level, regular releases **tested** on ~30 top-level HPC systems in US and Europe, code review, issue tracking, open mailing list
 - **Funded** by NSF grant #1550551
- **SP**ectral **E**instein **C**ode (SpEC) - black-holes.org
 - Simulating eXtreme Spacetimes (SXS) collaboration
 - Very accurate and efficient
 - **Funded** by Sherman Fairchild Foundation



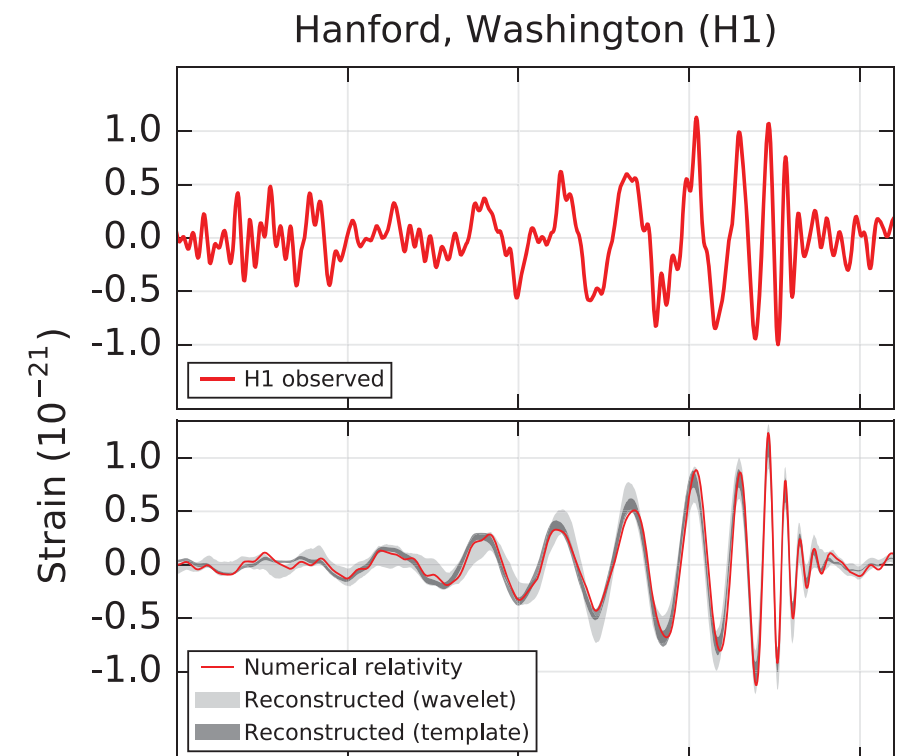
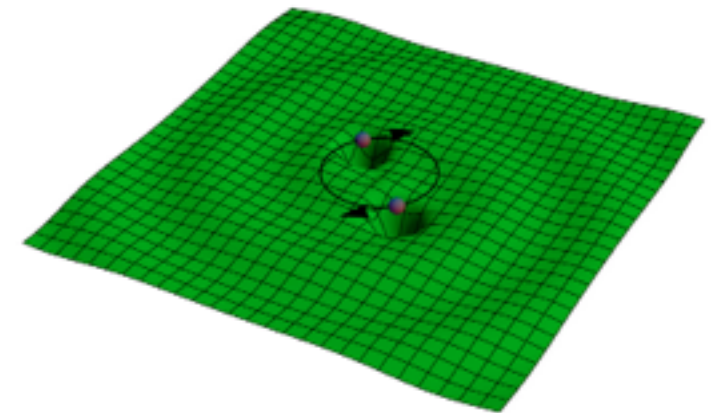
2. Gravitational waves

Gravitational wave strain from
simulation of GW150914

Understanding gravitational wave signals

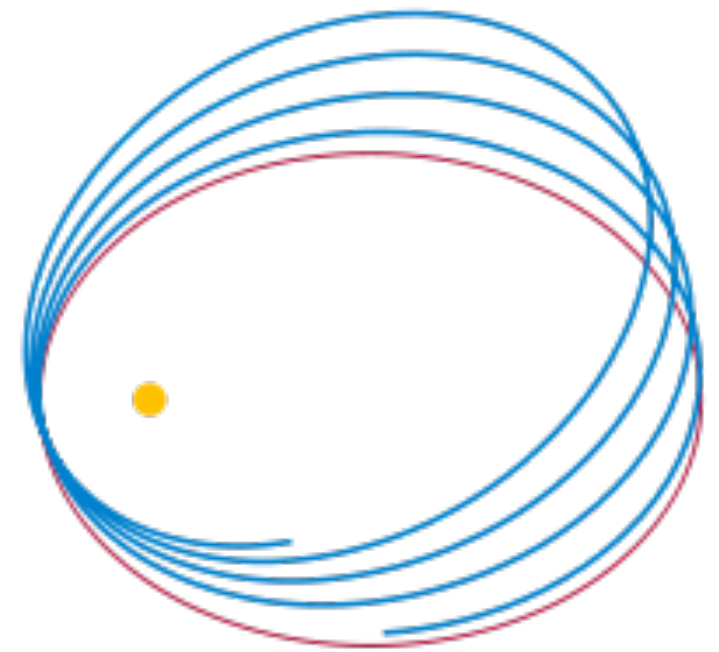
- GW detector measures **strain** in TT gauge
- **Matched filtering** to measure signal in **noisy** data
- Parameter estimation:
 - $\langle h_1, h_2 \rangle \equiv 4 \operatorname{Re} \int_0^\infty \frac{\tilde{h}_1(f) \tilde{h}_2^*(f)}{S_h(f)} df \quad \langle \hat{h}_\lambda, \hat{h}_{\text{det}} \rangle$
- Need accurate h_λ :
 - Numerical Relativity: weeks or **months** per waveform, vs **millions** needed
 - Fast models: PN+NR-inspired
- NR: (i) **calibrate** models, (ii) test **systematic** errors, (iii) model-independent **direct** parameter estimation
- In progress: automated NR **pipeline** using the **Einstein Toolkit** (with Huerta and Haas from NCSA) - open science

$$h_{ab} = \begin{pmatrix} h_+ & h_\times \\ h_\times & -h_+ \end{pmatrix}$$



The relativistic 2 body problem: Eccentric case

- Eccentric binary systems **circularise** as E and L are emitted [*Peters 1964*]
- LIGO: **circular only**
- Dense stellar environments → non-negligible waveform eccentricity
- Measure/bound eccentricity of **GW events** such as GW150914?
- **Eccentric waveform model:** compare with GW data
 - Use **Post-Newtonian** approximation and **Numerical Relativity**



Post-Newtonian model

- Large separation: existing **post-Newtonian** approximation:

$$\begin{bmatrix} r(t) \\ \phi(t) \end{bmatrix} = \text{expansion in } (v/c)$$

- Breaks down when **$v \sim c$**
- First **comparison with NR** [IH et al. 2010]:
 - Good agreement; depends on **subtleties of PN** model

Numerical Relativity simulations

- ~20 new **eccentric NR simulations**

- ~25 GW cycles with the **SpEC** code

- Non-spinning

- Initial eccentricity $e \leq 0.2$

- $q = m_1/m_2 \leq 3$

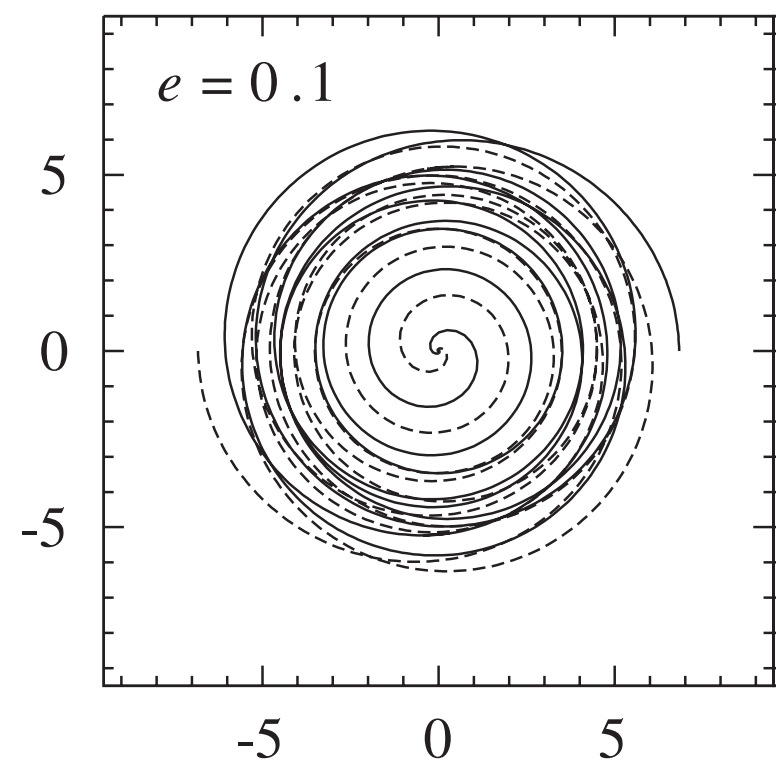
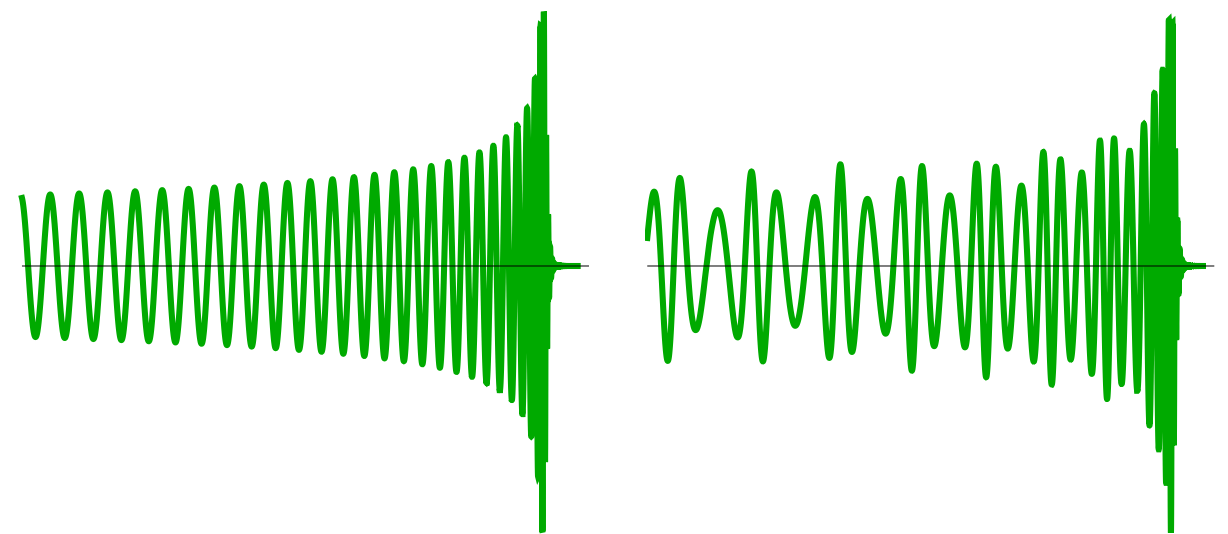
- Eccentricity did not bias **GW150914 parameter estimation**

[Pürrer, ..., IH et al 2016]

- Eccentric binaries **circularise** just before the merger (extending *[IH et al., 2008]*)

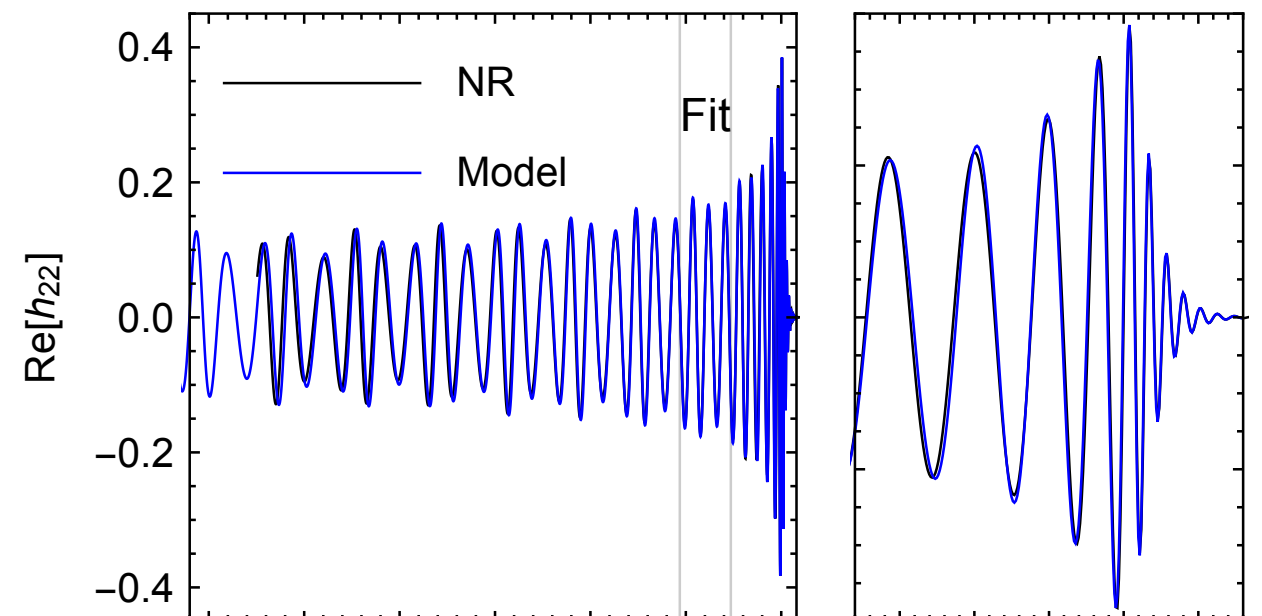
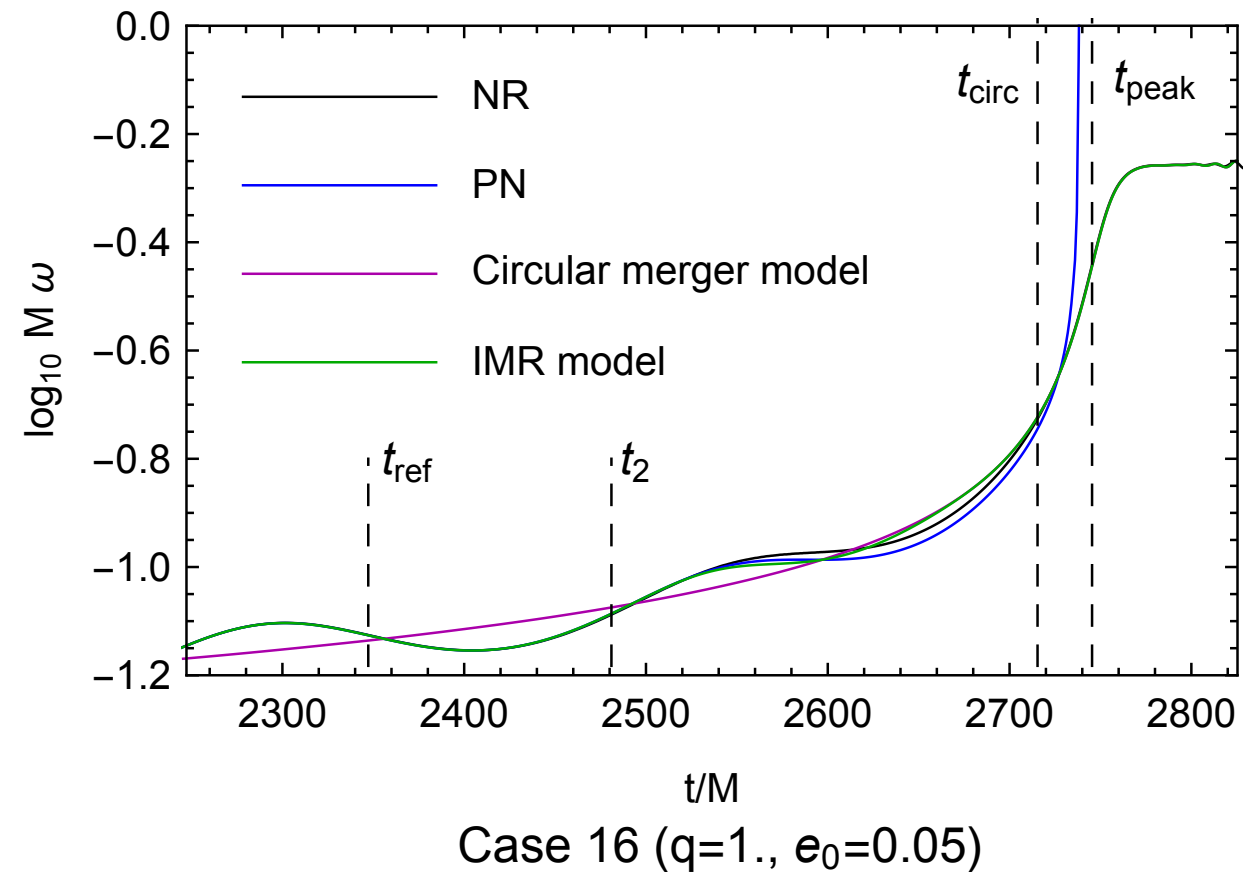
$e_0 = 0.00$

$e_0 = 0.15$



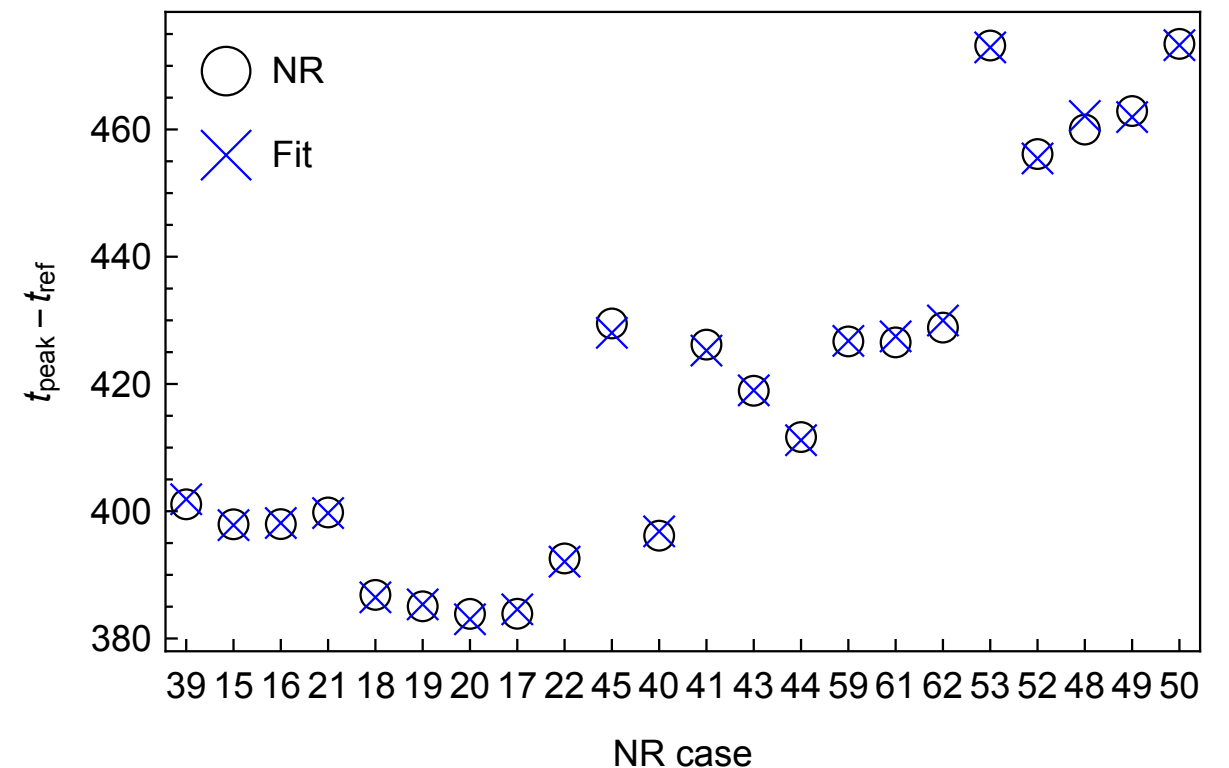
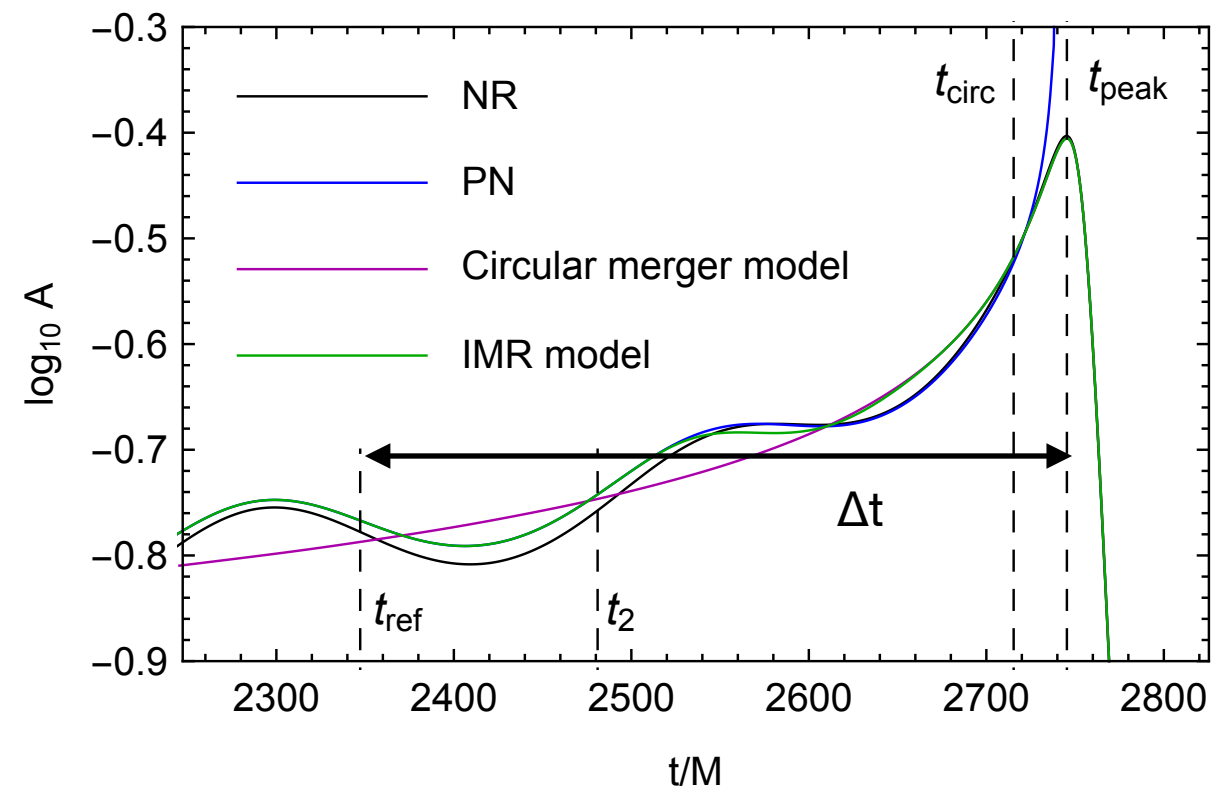
Eccentric waveform model construction

- Inspiral:
 - Use existing eccentric **post-Newtonian** model
- Merger:
 - Use existing **circular** model (justified from observed circularisation)
 - Here, we **interpolate** several equal-mass non-spinning waveforms
 - Smoothly **blend** inspiral and merger



Calibration

- **Blending parameters** from NR simulations
- Most important:
 - Δt determining peak of waveform
 - $\Delta t(q, e, l) = \Delta t_0 + a_1 e + a_2 e^2 + b_1 q + b_2 q^2 + c_1 e \cos(l + c_2)$

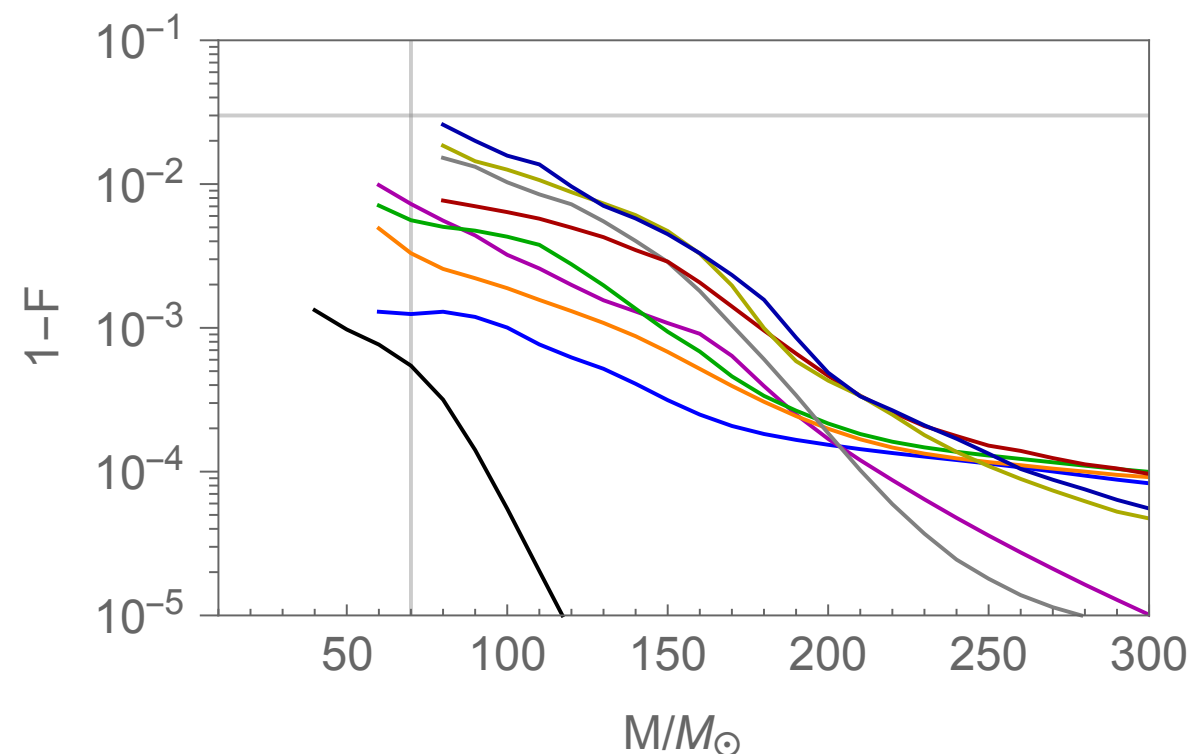


Results

- Now: for configuration like **GW150914**, model **faithfulness** with NR waveform > 97% for systems with

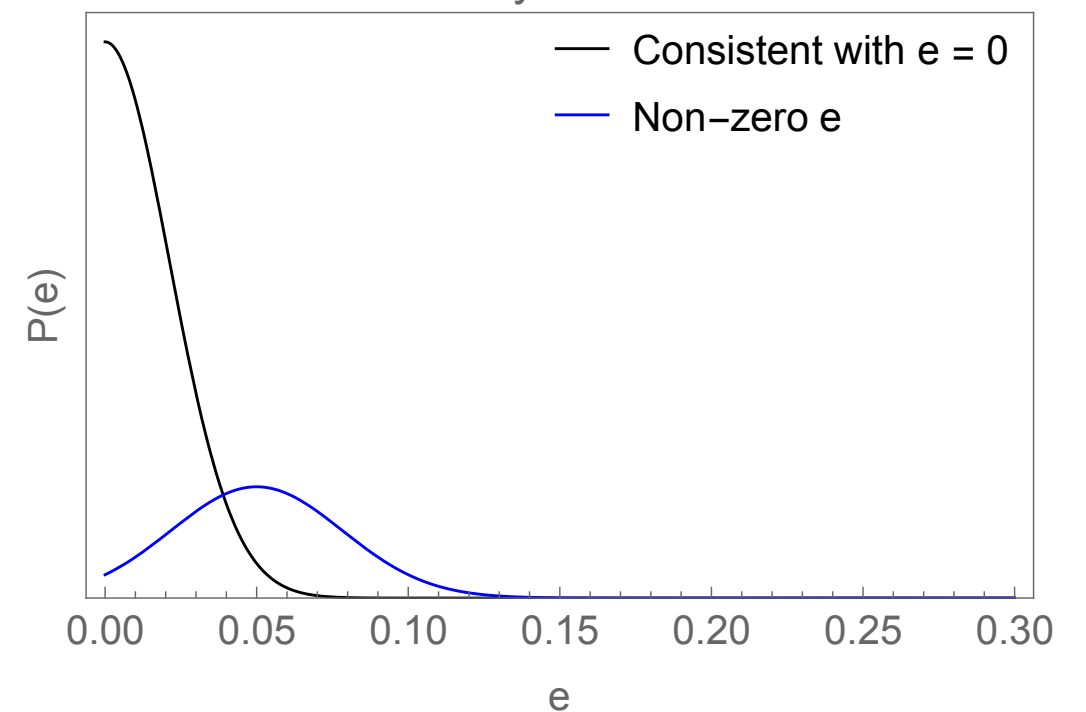
- Total mass > 93 Msun for $e < 0.08$
- Total mass > 70 Msun for $e < 0.05$

$$F = \langle h_1 | h_2 \rangle = \max_{\phi_c, t_c} \frac{(h_1(\phi_c, t_c) | h_2)}{\sqrt{(h_1 | h_1)(h_2 | h_2)}}$$



- Future:
 - Include spin
 - Parameter estimation on GW data

Hypothetical parameter estimation of eccentricity for a GW event



Outlook

- NR is **only solution** to Einstein's equations in dynamical strong-field
- LIGO parameter estimation **critically dependent** on NR waveforms
- Soon: **eccentricity** will be measurable
- Some plans...
 - **Eccentric** models for LIGO and LISA with spin
 - Waveforms from high **mass ratio** and high **spin** systems
 - Fully understand numerical **convergence** of NR AMR simulations
 - Design new **NR approximation** methods for **$q \sim 100-1000$**
 - **Mathematically-rigorous** computation of GWs in NR simulations
 - Task-based **parallelism** and improved **numerical methods** for x10 (?) simulation performance

